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| 10/829,364 | 04/22/2004 | Akifumi Yagaguchi | 0020-5252PUS1 | 7085 |
| | 2590 04/23/200 ART KOLASCH & BI | EXAMINER | | |
| PO BOX 747 FALLS CHURCH, VA 22040-0747 | | | WYATT, KEVIN S | |
| | | | ART UNIT | PAPER NUMBER |
| | | | 2878 | |
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| SHORTENED STATUTORY | PERIOD OF RESPONSE | NOTIFICATION DATE | . DELIVERY MODE | |
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mailroom@bskb.com

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| | Application No. | Applicant(s) | | | | |
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| Office Action Summany | 10/829,364 | YAGAGUCHI ET AL. | | | | |
| Office Action Summary | Examiner | Art Unit | | | | |
| | Kevin Wyatt | 2878 | | | | |
| The MAILING DATE of this communication app Period for Reply | ears on the cover sheet with the c | orrespondence address | | | | |
| A SHORTENED STATUTORY PERIOD FOR REPLY WHICHEVER IS LONGER, FROM THE MAILING DA Extensions of time may be available under the provisions of 37 CFR 1.13 after SIX (6) MONTHS from the mailing date of this communication. If NO period for reply is specified above, the maximum statutory period was Failure to reply within the set or extended period for reply will, by statute, Any reply received by the Office later than three months after the mailing earned patent term adjustment. See 37 CFR 1.704(b). | ATE OF THIS COMMUNICATION 16(a). In no event, however, may a reply be tim iill apply and will expire SIX (6) MONTHS from cause the application to become ABANDONE | lely filed the mailing date of this communication. D (35 U.S.C. § 133). | | | | |
| Status | · . | | | | | |
| 1) Responsive to communication(s) filed on 25 Ja | nuary 2007. | | | | | |
| 2a)⊠ This action is FINAL . 2b)☐ This | action is non-final. | | | | | |
| 3) Since this application is in condition for allowance except for formal matters, prosecution as to the merits is | | | | | | |
| closed in accordance with the practice under Ex parte Quayle, 1935 C.D. 11, 453 O.G. 213. | | | | | | |
| Disposition of Claims | | | | | | |
| 4) Claim(s) 1-15 is/are pending in the application. 4a) Of the above claim(s) is/are withdrawn from consideration. 5) Claim(s) is/are allowed. 6) Claim(s) 1-5 and 7-15 is/are rejected. 7) Claim(s) 6 is/are objected to. 8) Claim(s) are subject to restriction and/or election requirement. | | | | | | |
| Application Papers | | | | | | |
| 9) The specification is objected to by the Examiner 10) The drawing(s) filed on is/are: a) access Applicant may not request that any objection to the or Replacement drawing sheet(s) including the correction in the original origina | epted or b) objected to by the Edrawing(s) be held in abeyance. See on is required if the drawing(s) is obj | e 37 CFR 1.85(a). ected to. See 37 CFR 1.121(d). | | | | |
| Priority under 35 U.S.C. § 119 | 41 | | | | | |
| 12) Acknowledgment is made of a claim for foreign a) All b) Some * c) None of: 1. Certified copies of the priority documents 2. Certified copies of the priority documents 3. Copies of the certified copies of the prior application from the International Bureau * See the attached detailed Office action for a list of | s have been received. s have been received in Applicati ity documents have been receive (PCT Rule 17.2(a)). | on No ed in this National Stage | | | | |
| • | • | | | | | |
| Attachment(s) | | | | | | |
| Notice of References Cited (PTO-892) Notice of Draftsperson's Patent Drawing Review (PTO-948) Information Disclosure Statement(s) (PTO/SB/08) Paper No(s)/Mail Date Other: | | | | | | |
| S. Patent and Trademark Office | | | | | | |

DETAILED ACTION

1. This Office Action is in response to the Amendment after non-final and remarks filed on 01/25/2007. Currently, claims 1-15 are pending.

Claim Rejections - 35 USC § 102

2. The following is a quotation of the appropriate paragraphs of 35 U.S.C. 102 that form the basis for the rejections under this section made in this Office action:

A person shall be entitled to a patent unless -

- (b) the invention was patented or described in a printed publication in this or a foreign country or in public use or on sale in this country, more than one year prior to the date of application for patent in the United States.
- 3. Claims 1, 3-5, 7-8, 10-15 are rejected under 35 U.S.C. 102(b) as being anticipated by Ueda (U.S. Patent No. 5,796,470).

Regarding claim 1, Ueda shows in Figs. 1A-B, 2A, and 2B-C, an optical moving amount detecting device for detecting an amount of movement of a detection object, the detection object having a surface with certain surface conditions to reflect light cast thereon so that the light has a spatial output distribution, comprising: a light emitter (1, i.e., light source element or semiconductor laser, col. 4, lines 23-24), a light receiver (9, i.e., photo detector, col. 4, line 44), a first optical system (combination of lens units (11) and (12), and electro-optic elements 15a-b, col. 4, lines 31-41) for making light from the light emitter into a linear beam (beams 14a and 14b in Fig. 2A or 5a and 5b in Fig. 2B which are made linear in part by electro-optic elements 15a-b) having a length and a width, the length extending in parallel with a direction of movement detection object and casting the linear beam on the detection object, a second optical system (combination

of condenser lens (8) and lens unit (12), col. 4, line 43) by which a linear reflected beam that linear beam reflected (plurality of parallel beams (3), col. 1, lines 44-46) from the detection object made incident on the light receiver (col. 1, lines 44-58), a storage unit (storage means within signal processing means, col. 11, lines 1-7) for storing first output waveform signals that are outputted from the light receiver(9, i.e., photo detector) receiving the linear reflected beam (14a and 14b during initial displacement) at a first time point and that represent an output distribution of the linear reflected beam along a longitudinal direction thereof and that correspond to said surface conditions of the detection object, and storing second output waveform signals that are outputted from the light receiver receiving the linear reflected beam (14a and 14b during a second displacement) a second point and that represent an output distribution of the linear reflected beam along the longitudinal direction (signal processing means inherently stores the displacement of the object at some point in order to calculate object's velocity) thereof and that correspond to said surface conditions of the detection object, and a moving amount detecting unit (signal processing means, col. 11, lines 1-7) (see formulas 8 and 14) detecting an amount of shift between the first output waveform signals and the second output waveform signals in the longitudinal direction of the linear reflected beams and detecting a moving amount of the detection object on basis of the amount of shift (col. 6, lines 30-51).

Regarding claim 15, Ueda shows in Figs. 1A-B, 2A, and 2B-C, an optical moving amount detecting device for detecting an amount of movement of a detection object, the detection object having a surface with certain surface conditions to reflect light cast

thereon so that the light has a spatial output distribution, comprising: a light emitter (1, i.e., light source element or semiconductor laser, col. 4, lines 23-24), a light receiver (9, i.e., photo detector, col. 4, line 44), a first optical system (combination of lens units (11) and (12), and electro-optic elements 15a-b, col. 4, lines 31-41), including at least one first lens (15a-b, i.e., electro-optic elements), for making light from the light emitter into a linear beam having a length and a width, the length extending in parallel with a direction of movement of the detection object and casting the linear beam on the detection object (7), a second optical system (combination of condenser lens (8) and lens unit (12), col. 4, line 43), including at least one second lens (8, i.e., condenser lens), by which a linear reflected beam that is the linear beam (plurality of parallel beams (3), col. 1, lines 44-46) reflected from the detection object is made incident on the light receiver (9, i.e., photodetector)(col. 1, lines 44-58), a storage unit (storage means within signal processing means, col. 11, lines 1-7) for storing first output waveform signals (5a) that are outputted from the light receiver (9, i.e., photo detector) receiving the linear reflected beam (14a and 14b during initial displacement) at a first time point and that represent an output distribution of the linear reflected beam along a longitudinal direction (x coordinate, see Fig. 2B) thereof and that correspond to said surface conditions of the detection object, and storing second output waveform signals that are outputted from the light receiver receiving the linear reflected beam (14a and 14b during a second displacement) at a second time point and that represent an output distribution of the linear reflected beam along the longitudinal direction (signal processing means inherently stores the displacement of the object at some point in order to calculate

object's velocity) thereof and that correspond to said surface conditions of the detection object, and a moving amount detecting unit (signal processing means, col. 11, lines 1-7) (see formulas 8 and 14) for detecting an amount of shift of an output pattern appearing in the first output waveform signals based on an output pattern that is substantially identical appearing in the second output waveform signals in the longitudinal direction of the linear reflected beams, said output pattern corresponding to a common area with said surface conditions of the detection object and detecting a moving amount of the detection object on basis of the amount of shift, being the amount of shift of the corresponding common area (col. 6, lines 30-51).

Regarding claim 3, Ueda shows in Fig. 10 a deflector (131, i.e., mirror) for deflecting the linear reflected beam from the detection object (107, i.e., measured object) provided between the first optical system (the optics system within laser (10)) and the detection object.

Regarding claim 4, Ueda shows in Figs. 2B-C, that the moving amount detecting unit comprises a waveform correcting section (25, i.e., multiplier) for multiplying parts of the first output waveform signals and of the second output waveform signals by a plurality of coefficients (see equations 1-3, for doppler shift and light grating pitch interference) according to a light intensity distribution of the linear beam with respect to a longitudinal direction linear beams and thus correcting the light intensity distribution of the linear beam with respect to the longitudinal direction (col. 1, lines 56-63 and col. 2, lines 1-34).

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Regarding claim 5, Ueda shows in Figs. 2B-C, the moving amount detecting unit comprises a moving amount calculating section (combination of cpu (22), serodyne waveform generator (24), multiplier (25), and thermal conductor (19), col. 6, lines 66-67, and col. 7, lines 2-4) for determining correlation coefficients (see formulas 4-8) between first output waveform partial signals that are outputted the first time point from a first partial area corresponding part an image the linear reflected beam on the light receiver with respect to the longitudinal direction and plurality of sets second output waveform partial signals that are outputted the second time point from plurality partial areas corresponding a plurality of parts of an image of the linear reflected beam on the light receiver, determining a second partial area that results in a highest correlation coefficient at the second time point, and calculating the moving amount the detection object on basis of an amount of shift between the first partial area and the second partial area (see formulas 1-8).

Regarding claim 7, Ueda shows in Figs. 2B-C, an optical moving amount detecting device as claimed in claim 5, wherein the size of the whole area of the light receiver is equal to a sum of the size of the first partial area (area of beam (14a)), the moving amount of the image of the linear reflected beam which amount corresponds to the predetermined moving amount the detection object (7), and a predicted amount of positional shift of the detection object from the moving amount (col. 1, lines 56-63).

Regarding claim 8, Ueda shows in Figs. 2B, electronic equipment (combination of cpu (22) A/D converter (21) D/A converter (23), multiplier (25) and thermal conductor (19) comprising the optical moving amount detecting device as claimed in claim 1.

Regarding claim 10, Ueda shows in Figs. 1A-B, 2A, and 2B-C, an optical movement detector detecting movement of a detection object, the detection object having a surface with certain surface conditions to reflect light cast thereon so that the light has a spatial output distribution, comprising: a light emitter (1, i.e., light source element or semiconductor laser, col. 4, lines 23-24), a first optical system (11 and 12, i.e., lens units, col. 4, lines 31-33) projecting a light beam having a cross section having a length and a width on the detection object (7) such that the length extends parallel to a direction of movement (x coordinate) of the detection object (see Figs. 2B-C), a light receiver (9, i.e., photo detector, col. 4, line 44) receiving a reflection of the light beam from the detection object, a storage unit (22, i.e., cpu) for storing first output waveform signals from the light receiver at a first time and storing second output waveform signals from the light receiver at a second time wherein the first and second output waveform signals correspond to said surface conditions of the detection object, and a movement detecting unit detecting an amount of shift between the first output waveform signals and second output waveform signals and determining a movement amount of the detection object based on the detected amount of shift (col. 1, lines 56-63 and col. 2, lines 1-12).

Regarding claim 11, Ueda shows in Figs. 1A-B, 2A, and 2B-C, a method of optically detecting amount of movement of an object, the detection object having a surface with certain surface conditions to reflect light cast thereon so that the light has a spatial output distribution, comprising the steps of: projecting light (beams 5a-b or 14a-b) against the object (7) to form a generally rectangular image having a length and a

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width such that the length aligned with a direction of movement (x coordinate) of the object; detecting first reflection the generally rectangular image from the object at first time and outputting first waveform (5a) signals related to the first detected reflection (14a) and that correspond to said surface conditions of the object; detecting a second reflection of the generally rectangular image from the object at a second time and outputting second waveform signals (5a) related to the second detected reflection (14a) and that correspond to said surface conditions of the object; measuring an amount of waveform shift between the first output waveform and the second output waveform signals for a common area within said surface conditions of the object, an amount of object shift between the first time and the second time.

Regarding claim 12, Ueda shows in Fig. 2A a method of deflecting the first reflection of the generally rectangular image.

Regarding claim 13, Ueda discloses a method of multiplying a part of the first output waveform signals (5a) and a part of the second output waveform signals (5b) (col. 7, lines 2-5) a plurality of coefficients according to a light intensity distribution of the linear beam with respect to longitudinal direction of the linear beam (see formulas 1-8), and correcting the light intensity distribution of the linear beam with respect the longitudinal direction (col. 1, lines 56-63 and col. 2, lines 1-34).

Regarding claim 14, Ueda discloses a method of determining correlation coefficients between first output waveform partial signals outputted at the first time point from a first partial area corresponding to a part of the reflected image of the linear beam with respect to the longitudinal direction and a plurality of sets of second output

waveform partial signals outputted at the second time from plurality partial areas corresponding to a plurality of parts of the image of the linear beam (see formulas 4-8); determining a second partial area from the plurality of partial areas that results in a highest correlation coefficient at the second time, and calculating the amount movement of the object based on the shift between the first partial area and the second partial area (see formula 3 and 8, and col. 6, lines 34-51).

Claim Rejections - 35 USC § 103

- 4. The following is a quotation of 35 U.S.C. 103(a) which forms the basis for all obviousness rejections set forth in this Office action:
 - (a) A patent may not be obtained though the invention is not identically disclosed or described as set forth in section 102 of this title, if the differences between the subject matter sought to be patented and the prior art are such that the subject matter as a whole would have been obvious at the time the invention was made to a person having ordinary skill in the art to which said subject matter pertains. Patentability shall not be negatived by the manner in which the invention was made.
- 5. Claim 2 is rejected under 35 U.S.C. 103(a) as being unpatentable over Ueda (U.S. Patent No. 5,796,470) in view of Okada (U.S. Patent No. 6,754,246 B2).

Regarding claim 2, Ueda discloses the claimed invention as stated above. Ueda does not explicitly disclose that the light emitter is composed of a plurality of semiconductor laser devices disposed linearly. Okada shows in Fig. 1B a light emitter (1, i.e., light source apparatus) composed of a plurality of semiconductor laser devices (2, i.e., semiconductor laser arrays) disposed linearly. It would have been obvious to one skilled in the art to provide a light source apparatus such as disclosed in Okada to the device of Ueda for the purpose of improving overall parallelism of the laser beams, thus improving focusing performance of the device.

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6. Claim 9 is rejected under 35 U.S.C. 103(a) as being unpatentable over Ueda (U.S. Patent No. 5,796,470) in view of Costanza (U.S. Patent No. 5,204,620).

Regarding claim 9, Ueda discloses the claimed invention as stated above. Ueda does not disclose a conveying section conveying the detection object, and a controller for controlling the conveying section so as to align with a target position after conveyance, on basis of moving amount of the detection position of the detection object that is detected by the optical moving amount detecting device. Costanza shows in Figs. 1, 3 and 5, a conveyance processing system (photoreceptor belt) comprising: a conveying section (I₁, I₂, I₃ or I_m) conveying the detection object, and a controller (35, i.e., belt servo controller) for controlling the conveying section so as to align with a target position after conveyance, on basis of moving amount of the detection position of the detection object that is detected by the optical moving amount detecting device (see Fig. 5). It would have been obvious to one skilled in the art to provide the photoreceptor belt of Costanza to the apparatus of Ueda, for the purpose of providing the continuous motion needed for object's velocity measurements.

Allowable Subject Matter

- 6. Claim 6 is objected to as being dependent upon a rejected base claim, but would be allowable if rewritten in independent form including all of the limitations of the base claim and any intervening claims.
- 7. The following is a statement of reasons for the indication of allowable subject matter:

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Claim 6 has allowable subject matter because the prior art fails to disclose or make obvious, either singly or in combination, an optical moving amount detecting device comprising, in addition to the other recited features of the claim, "wherein a size of the first partial area of the light receiver such that the first output waveform partial signals outputted from the first partial area can be discriminated from signals outputted at the first time point from areas other than the first partial area the light receiver and wherein a size of a whole area the light receiver is not smaller than a sum of the size of the first partial area and of a moving amount of an image of the linear reflected beam which amount corresponds to a predetermined moving amount of the detection object."

Response to Arguments

7. Applicant's arguments filed 01/25/2007 have been fully considered but they are not persuasive.

In response to applicant's arguments that Ueda does not utilize surface conditions in determining an amount of movement of a detection object, the examiner disagrees. Ueda indicates in col. 2, lines 23-40, that utilizing surface conditions is a part of determining amount of movement of the detection object.

In response to applicant's arguments that Okada that there would be no reason to use the focusing to taught by Okada and much less improve focusing, in the frequency shifter, the examiner points out that the arrangement disclosed in Okada exibits a much high degree of parallelism of the semiconductor laser beams which would provide an overall improvement in the parallel beams of Ueda.

Conclusion

8. The prior art made of record and not relied upon is considered pertinent to applicant's disclosure.

Tekemori (U.S. Patent No. 5,361,131) optical displacement measuring apparatus utilizing fourier transform method.

Sueda (U.S. Patent No. 4,698,511) document sheet size or position recognition device.

9. Applicant's amendment necessitated the new ground(s) of rejection presented in this Office action. Accordingly, **THIS ACTION IS MADE FINAL**. See MPEP § 706.07(a). Applicant is reminded of the extension of time policy as set forth in 37 CFR 1.136(a).

A shortened statutory period for reply to this final action is set to expire THREE MONTHS from the mailing date of this action. In the event a first reply is filed within TWO MONTHS of the mailing date of this final action and the advisory action is not mailed until after the end of the THREE-MONTH shortened statutory period, then the shortened statutory period will expire on the date the advisory action is mailed, and any

extension fee pursuant to 37 CFR 1.136(a) will be calculated from the mailing date of the advisory action. In no event, however, will the statutory period for reply expire later than SIX MONTHS from the date of this final action.

Any inquiry concerning this communication or earlier communications from the examiner should be directed to Kevin Wyatt whose telephone number is (571)-272-5974. The examiner can normally be reached on Monday-Friday.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Georgia Epps can be reached on (571)-272-2328. The fax phone number for the organization where this application or proceeding is assigned is 571-273-8300.

Information regarding the status of an application may be obtained from the Patent Application Information Retrieval (PAIR) system. Status information for published applications may be obtained from either Private PAIR or Public PAIR. Status information for unpublished applications is available through Private PAIR only. For more information about the PAIR system, see http://pair-direct.uspto.gov. Should you have questions on access to the Private PAIR system, contact the Electronic Business Center (EBC) at 866-217-9197 (toll-free).

K.W.

Gedzgia Epps
Supervisory Patent Examiner
Technology Center 2800